

## Midterm Study Guide

### Midterm Time and Place:

- Wednesday, March 2, 9:10-10am
- Packard 258 (*our usual room*)

### Format:

The test will be held in class. You can expect the following types of questions: true/false, short answer, and smaller versions of homework problems. It will be closed book and closed notes. However, you may bring one 8 ½ x 11” “cheat sheet” with handwritten notes on one-side only. Also, all calculators, PDAs, and cell phones must be put away for the duration of the test.

### Coverage:

In general, anything from the assigned reading or lecture could be on the test. In order to help you focus, I have provided a **partial list** of topics that you should know below. In some cases, I have explicitly listed topics that you do not need to know. In addition, you do not need to memorize the pseudo-code for any algorithm, but you should be able to apply the principles of the major algorithms to a problem as we have done in class and on the homework.

- Ch. 1 – Introduction
  - rationality
  - definitions of “artificial intelligence”
  - The Turing Test
  - **you do not need to know:**
    - dates and history
- Ch. 2 - Agents
  - PEAS descriptions
    - performance measure, environment, actuators, sensors
  - properties of task environments
    - fully observable vs. partially observable, deterministic vs. stochastic vs. strategic, episodic vs. sequential, static vs. dynamic, discrete vs. continuous, single agent vs. multiagent
  - agent architectures
    - simple reflex agents, goal-based agents, utility-based agents
  - **you do not need to know:**
    - learning agents
- Ch. 3 – Search (Sect. 3.1-3.5)
  - problem description
    - initial state, actions (successor function), goal test, path cost, step cost
  - tree search
    - expanding nodes, fringe
    - branching factor
  - uninformed search strategies
    - breadth-first, depth-first, uniform cost
    - similarities and differences / benefits and tradeoffs between strategies

- evaluation criteria
      - completeness, optimality, time complexity, space complexity
  - **you do not need to know:**
    - depth-limited, iterative deepening or bidirectional search
    - the exact  $O()$  for any strategy's time/space complexity (*but you should know relative complexity*)
- Ch. 4 – Informed Search (Sect. 4.1-4.2)
  - best first search
  - evaluation function, heuristics
  - strategies
    - greedy search, A\*
    - admissible heuristics
    - similarities and differences / benefits and tradeoffs between strategies
  - **you do not need to know:**
    - details of proof that A\* is optimal if  $h(n)$  is admissible
    - memory bounded heuristic search
    - learning heuristics from experience
- Ch. 6 - Game playing (Sect. 6.1-6.2, 6.4, 6.6-6.8)
  - two-player zero-sum game
  - problem description
    - initial state, actions (successor function), terminal test, utility function
  - minimax algorithm
  - optimal decision vs. imperfect real-time decisions
  - evaluation function, cutoff-test
  - **you do not need to know:**
    - alpha-beta pruning
- Ch. 7 – Logical Agents (Sect. 7.1-7.4)
  - knowledge-based agents
    - TELL, ASK
  - propositional logic
    - syntax and semantics
  - entailment, models, truth tables
  - valid, satisfiable, unsatisfiable
  - inference algorithms
    - criteria: sound, complete
  - model checking
  - **you do not need to know:**
    - details of the Wumpus world
- Ch. 8 – First-Order Logic (Sect. 8.1-8.5)
  - syntax and semantics
    - be able to translate English sentences into logic sentences
  - quantification
    - existential, universal
  - domain, model, interpretation

- Ch. 9 – Inference in First-Order Logic (Sect. 9.1-9.2, 9-4)
  - substitution, unification
    - most general unifier
  - backward-chaining
    - pros / cons
  - **you do not need to know:**
    - inference rules, skolemization
    - constraint logic programming
    - negation as failure
- “Intro to Prolog Programming” Reading, Ch. 1
  - syntax
    - be able to write rules and facts in Prolog
    - translating to FOL and vice versa
  - backward-chaining, depth-first search
    - be able to find the answers to a goal given a simple Prolog program